

WHAT IS CLAIMED IS:

1. A method for creating a composite image of at least  
5 one object, the method comprising:

recording a plurality of images of the object using an  
image recording device moving along a path;

obtaining position information of the image recording  
device as the image recording device moves along the path;

10 associating the position information with the plurality of  
images; and

processing image data acquired from the plurality of  
images to create a composite image representing the object.

15 2. The method of claim 1, wherein the object is located  
on a first side of the path and the composite image simulates  
a view of the object from a particular location on a second side  
of the path opposite from the first side.

20 3. The method of claim 2, wherein the processing of the  
image data comprises:

identifying a plurality of optical rays originating from  
the particular location;

25 selecting for each optical ray an image including a  
corresponding optical ray originating from a position on the  
path;

30 extracting image data for the corresponding optical ray  
from the selected images; and

combining the extracted image data to form the composite  
image.

4. A method for creating a composite image of at least  
35 one object, the method comprising:

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recording a plurality of images of the objects using an image recording device moving along a path;

5 obtaining position information of the image recording device as the image recording device moves along the path;

associating the position information with the plurality of images; and

10 processing image data acquired from the plurality of images to create a composite image depicting a view of the object from a particular location.

15 5. The method of claim 4, wherein the object is located on a first side of the path and the composite image simulates a view of the object from the particular location on a second side of the path opposite from the first side.

20 6. The method of claim 4, wherein the obtaining of position information comprises obtaining Global Positioning System (GPS) data.

25 7. The method of claim 4, wherein the obtaining of position information comprises:

obtaining acceleration information of the image recording device as the image recording device moves along the path; and

deriving the position information from the acceleration information.

30 8. The method of claim 4, wherein the obtaining of position information comprises deriving the position information of the image recording device at a particular time by computing a motion of objects in a plurality of images closest to the  
35 particular time.

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9. The method of claim 4, wherein the associating of the position information comprises correlating times associated with  
5 the position information to times of acquisition of the plurality of images.

10. The method of claim 4, wherein the processing of the image data comprises:

10 identifying a plurality of optical rays originating from the particular location;

selecting for each optical ray an image including a corresponding optical ray originating from a position on the path;  
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extracting image data for the corresponding optical ray from the selected images; and

combining the extracted image data to form the composite image.

20 11. The method of claim 10, wherein the selecting of an image for each optical ray comprises:

determining the particular position on the path where the image recording device would have been located for recording an  
25 image including the corresponding optical ray;

calculating a time associated with the determined position; and

identifying an image recorded at the calculated time.

30 12. The method of claim 10, wherein the selecting of an image for each optical ray comprises:

determining the particular position on the path where the image recording device would have been located for recording an  
35 image including the corresponding optical ray;

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calculating a time associated with the determined position;

5 selecting an image recorded closest to the calculated time.

13. The method of claim 10, wherein the selecting of an image for each optical ray comprises:

10 determining the particular position on the path where the image recording device would have been located for recording an image including the corresponding optical ray;

calculating a time associated with the determined position;

15 selecting a plurality of images recorded closest to the calculated time;

computing a motion of objects in the selected images; and

20 creating a new image frame for the calculated time based on the computed motion of objects.

14. The method of claim 4, wherein the image data comprises a set of pixel values.

25 15. The method of claim 4, wherein the recording of the images comprises recording the images from multiple viewing directions using multiple image recording devices.

30 16. A method for creating a composite image database of a particular geographic area, the method comprising:

recording a plurality of images of a series of objects using an image recording device moving along a path;

35 obtaining position information of the image recording device as the image recording device moves along the path;

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associating the position information with the plurality of images;

5 processing image data acquired from the plurality of images to create a composite image depicting a view of the series of objects from a particular location;

partitioning the path into a plurality of discrete segments;

10 associating the composite image to one of the discrete segments ; and

storing the composite image and association information in the composite image database.

15 17. The method of claim 16, wherein the recording of the images comprises recording the images from multiple viewing directions using multiple image recording devices.

20 18. The method of claim 16, wherein the obtaining of position information comprises obtaining Global Positioning System (GPS) data.

25 19. The method of claim 16, wherein the obtaining of position information comprises:

obtaining acceleration information of the image recording device as the image recording device moves along the path; and

30 deriving the position information from the acceleration information.

20. The method of claim 16, wherein the obtaining of position information comprises deriving the position information of the image recording device at a particular time by computing  
35 a motion of objects in a plurality of images closest to the particular time.

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21. The method of claim 16, wherein the associating of  
5 the position information comprises correlating times associated  
with the position information to times of acquisition of the  
plurality of images.

22. The method of claim 16, wherein the object is located  
10 on a first side of the path and the composite image simulates  
a view of the object from the particular location on a second  
side of the path opposite from the first side.

23. The method of claim 16, wherein the processing of the  
15 image data comprises:

identifying a plurality of optical rays originating from  
the particular location;

selecting for each optical ray an image including a  
20 corresponding optical ray originating from a position on the  
path;

extracting image data for the corresponding optical ray  
from the selected images; and

25 combining the extracted image data to form the composite  
image.

24. The method of claim 23, wherein the selecting of an  
image for each optical ray comprises:

30 determining the particular position on the path where the  
image recording device would have been located for recording an  
image including the corresponding optical ray;

calculating a time associated with the determined  
position; and

35 identifying an image recorded at the calculated time.

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25. The method of claim 23, wherein the selecting of an image for each optical ray comprises:

5 determining the particular position on the path where the image recording device would have been located for recording an image including the corresponding optical ray;

calculating a time associated with the determined position; and

10 selecting an image recorded closest to the calculated time.

26. The method of claim 23, wherein the selecting of an image for each optical ray comprises:

15 determining the particular position on the path where the image recording device would have been located for recording an image including the corresponding optical ray;

20 calculating a time associated with the determined position;

selecting a plurality of images recorded closest to the calculated time;

calculating a motion of objects in the selected images; and

25 creating a new image frame for the calculated time based on the computed motion of objects.

27. The method of claim 16, wherein the image data comprises a set of pixel values.

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28. The method of claim 16, wherein the partitioning of the path into a plurality of discrete segments comprises:

detecting an intersection on the path; and

35 identifying the position of the intersection.

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29. The method of claim 28 wherein the detecting of the  
intersection comprises detecting a point of maximum curvature  
5 on the path.

30. The method of claim 16 wherein each discrete segment  
is associated with a plurality of composite images, each  
composite image depicting a portion of the associated segment.  
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31. The method of claim 16, wherein each discrete segment  
is a portion of a street and the method further comprises  
associating each discrete segment with a street name and number  
range.  
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32. In a system including an image database and a user  
terminal having a screen and an input device, a method for  
visually navigating a geographic area from a user terminal, the  
method comprising:  
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storing a plurality of images in the image database  
representing substantially all static objects within the  
geographic area;

identifying a current location in the geographic area;  
25 retrieving an image corresponding to the current location  
from the image database;

monitoring a change of the current location in the  
geographic area; and

30 retrieving an image corresponding to the changed location.

33. The method of claim 32, wherein image database  
resides at a remote site and a host computer at the remote site  
receives a request via a communications network for an image  
35 corresponding to the current or changed location, retrieves the  
requested image from the image database, and transmits the

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retrieved image to the user terminal via the communications network.

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34. The method of claim 32, wherein the image database resides at the user terminal and the method further comprises:

displaying the image corresponding to the current location on the screen of the user terminal; and

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updating the image on the screen with the image corresponding to the changed location.

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35. The method of claim 32 further comprising retrieving a map of a portion of the geographic area for displaying the map on the screen of the user terminal.

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36. The method of claim 35, wherein the current or changed location is identified by a user selection of the location on the map using the input device.

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37. The method of claim 32, wherein the current or changed location is identified by a specific address entered by the user using the input device.

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38. The method of claim 32, wherein the retrieving of the image corresponding to the current or changed location comprises:

identifying a street segment including the current or changed location;

identifying a position on the street segment corresponding to the current or changed location; and

identifying an image associated with said position.

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39. The method of claim 38, wherein the image simulates  
a view of objects on one side of the street segment and the  
5 method further comprises retrieving a second image depicting a  
view of objects on an opposite side of the street segment in  
response to a user request.

40. The method of claim 32, wherein the image is a  
10 composite image created by processing a plurality of image  
frames acquired from an image recording device moving through  
the geographic area.

41. The method of claim 32 further comprising:  
15 displaying an indicia that information is available about  
an object in the image; and  
retrieving information about the object in response to a  
user request to display the information on the screen of the  
20 user terminal.

42. The method of claim 32 further comprising:  
displaying a navigation button on the screen of the user  
terminal; and  
25 retrieving the image associated with the changed location  
from the image database upon actuation of the navigation button  
using the user input device.

43. The method of claim 32 further comprising:  
30 displaying a map of a portion of the geographic area;  
identifying the current location with an identifier on the  
map; and  
advancing the identifier on the map from the current  
35 location to the changed location.

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44. The method of claim 32 further comprising identifying a current viewing direction associated with the retrieved image.

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45. A system for creating a composite image of a series of objects, the system comprising:

an image recording device moving along a path and recording a plurality of images of the objects;

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a means for receiving position information of the image recording device as the image recording device moves along the path; and

a processor receiving the plurality of images and position information, the processor being operable to execute program instructions including:

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associating the position information with the plurality of images; and

processing image data acquired from the plurality of images to create a composite image depicting a view of the object from a particular location.

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46. The system of claim 45 wherein multiple image recording devices record the images from multiple viewing directions.

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47. The system of claim 45, wherein the object is located on a first side of the path and the composite image simulates a view of the object from the particular location on a second side of the path opposite from the first side.

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48. The system of claim 45, wherein the means for receiving position information comprises means for obtaining acceleration information of the image recording device as the image recording device moves along the path.

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49. The system of claim 45, wherein the means for  
5 receiving position information comprises means for receiving GPS  
data.

50. The system of claim 45, wherein the associating of  
10 the position information comprises correlating times associated  
with the position information to times of acquisition of the  
plurality of images.

51. The system of claim 45, wherein the processing of the  
15 image data comprises:

identifying a plurality of optical rays originating from  
the particular location;

selecting for each optical ray an image including a  
corresponding optical ray originating from a position on the  
20 path;

extracting image data for the corresponding optical ray  
from the selected images; and

combining the extracted image data to form the composite  
image.  
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52. The system of claim 51, wherein the selecting of an  
image for each optical ray comprises:

determining the particular position on the path where the  
30 image recording device would have been located for recording an  
image including the corresponding optical ray;

calculating a time associated with the determined  
position; and

identifying an image recorded at the calculated time.  
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53. The system of claim 51, wherein the selecting of an image for each optical ray comprises:

5 determining the particular position on the path where the image recording device would have been located for recording an image including the corresponding optical ray;

calculating a time associated with the determined position;

10 selecting an image recorded closest to the calculated time.

54. The system of claim 51, wherein the selecting of an image for each optical ray comprises:

15 determining the particular position on the path where the image recording device would have been located for recording an image including the corresponding optical ray;

calculating a time associated with the determined position;

20 selecting a plurality of images recorded closest to the calculated time;

calculating a motion of objects in the selected images; and

25 creating a new image frame for the calculated time based on the computed motion of objects.

55. The system of claim 45, wherein the image data comprises a set of pixel values.

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56. A system for creating a composite image database of a particular geographic area, the system comprising:

35 an image recording device moving along a path and recording a plurality of images of a series of objects;

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means for obtaining position information of the image  
recording device as the image recording device moves along the  
5 path;

means for associating the position information with the  
plurality of images;

means for processing image data acquired from the  
plurality of images to create a composite image depicting a view  
10 of the series of objects from a particular location;

means for partitioning the path into a plurality of  
discrete segments;

means for associating the composite image to one of the  
discrete segments; and  
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means for storing the composite image and association  
information in the composite image database.

57. The system of claim 56 wherein multiple image  
recording devices record the images from multiple viewing  
20 directions.

58. The system of claim 56, wherein the means for  
associating comprises means for correlating times associated  
25 with the position information to times of acquisition of the  
plurality of images.

59. The system of claim 56, wherein the object is located  
30 on a first side of the path and the composite image simulates  
a view of the object from the particular location on a second  
side of the path opposite from the first side.

60. The system of claim 56, wherein the means for  
35 processing the image data comprises:

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means for identifying a plurality of optical rays  
originating from the particular location;

5 means for selecting for each optical ray an image  
including a corresponding optical ray originating from a  
position on the path;

means for extracting image data for the corresponding  
optical ray from the selected images; and

10 means for combining the extracted image data to form the  
composite image.

61. The system of claim 60, wherein the means for  
15 selecting an image for each optical ray comprises:

means for determining the particular position on the path  
where the image recording device would have been located for  
recording an image including the corresponding optical ray;

20 means for calculating a time associated with the  
determined position; and

means for identifying an image recorded at the calculated  
time.

62. The system of claim 60, wherein the means for  
25 selecting an image for each optical ray comprises:

means for determining the particular position on the path  
where the image recording device would have been located for  
recording an image including the corresponding optical ray;

30 means for calculating a time associated with the  
determined position; and

means for selecting an image recorded closest to the  
calculated time.

63. The system of claim 60, wherein the means for  
35 selecting of an image for each optical ray comprises:

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means for determining the particular position on the path  
where the image recording device would have been located for  
5 recording an image including the corresponding optical ray;

means for calculating a time associated with the  
determined position;

means for selecting a plurality of images recorded closest  
to the calculated time;

10 means for calculating a motion of objects in the selected  
images; and

means for creating a new image frame for the calculated  
time based on the computed motion of objects.

15 64. The system of claim 56, wherein the image data  
comprises a set of pixel values.

65. The system of claim 56, wherein the means for  
20 partitioning the path comprises:

means for detecting an intersection on the path; and  
means for identifying the position of the intersection.

25 66. The system of claim 56 wherein each discrete segment  
is associated with a plurality of composite images, each  
composite image depicting a portion of the associated segment.

30 67. The system of claim 56, wherein each discrete segment  
is a portion of a street and the system further comprises means  
for associating each discrete segment with a street name and  
number range.

35 68. A system for visually navigating a geographic area  
from a user terminal, the system comprising:

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means for storing a plurality of images in the image  
database representing substantially all static objects within  
5 the geographic area;

means for identifying a current location in the geographic  
area;

means for retrieving an image corresponding to the current  
location from the image database;

10 means for monitoring a change of the current location in  
the geographic area; and

means for retrieving an image corresponding to the changed  
location.

15 69. The system of claim 68, wherein the image database  
resides at a remote site and the system further comprises a host  
computer including means for receiving a request for an image  
corresponding to the current or changed location, means for  
20 retrieving the requested image from the image database, and  
means for transmitting the retrieved image to the user terminal.

70. The system of claim 68, wherein the image database  
resides at the user terminal and the system further comprises:  
25 a display screen for displaying the image of the current  
location; and

means for updating the image on the screen with the image  
corresponding to the changed location.

30 71. The system of claim 68 further comprising means for  
retrieving a map of a portion of the geographic area for  
displaying the map on the screen of the user terminal.

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72. The system of claim 71, wherein the current or  
changed location is identified by a user selection of the  
5 location on the map using in the input device.

73. The system of claim 68, wherein the current or  
changed location is identified by a specific address entered by  
the user using an input device.

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74. The system of claim 68, wherein the means for  
retrieving the image corresponding to the current or changed  
location comprises:

15 means for identifying a street segment including the  
current or changed location;

means for identifying a position on the street segment  
corresponding to the current or changed location; and

20 means for identifying an image associated with said  
position..

75. The system of claim 74, wherein the image simulates  
a view of objects on one side of the street segment and the  
system further comprises means for retrieving a second image  
25 depicting a view of objects on an opposite side of the street  
segment in response to a user request.

76. The system of claim 68 further comprising means for  
30 processing a plurality of image frames acquired from an image  
recording device moving through the geographic area.

77. The system of claim 68 further comprising:  
means for indicating that information is available about  
35 an object in the image;

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means for retrieving information about the object in  
response to a user request to display the information on the  
5 screen of the user terminal.

78. The system of claim 68 further comprising:  
means for navigating the image database; and  
means for retrieving the image associated with the next  
10 location from the image database as the user navigates the image  
database.

79. The system of claim 68 further comprising:  
15 means for displaying a map of a portion of the geographic  
area;  
means for identifying the current location on the map; and  
means for identifying the next location on the map as the  
user navigates the image database.

80. The system of claim 68 further comprising means for  
identifying a current viewing direction associated with the  
retrieved image.

25 81. A computer-readable medium comprising:  
a program code embodied in the computer readable medium  
for creating a composite image of a series of objects from a  
plurality of images acquired by an image recording device moving  
30 along a path, the computer-readable program segment comprising  
instructions for performing the steps of:

identifying a plurality of optical rays originating from  
a particular location;

selecting for each optical ray an image including a  
35 corresponding optical ray originating from a position on the  
path;

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extracting image data for the corresponding optical ray  
from the selected images; and

5 combining the extracted image data to form the composite  
image.

82. The computer-readable medium of claim 79, wherein the  
step of selecting an image for each optical ray comprises:

10 determining the particular position on the path where the  
image recording device would have been located for recording an  
image including the corresponding optical ray;

calculating a time associated with the determined  
position; and

15 identifying an image recorded at the calculated time.

83. The computer-readable medium of claim 79, wherein the  
step of selecting an image for each optical ray comprises:

20 determining the particular position on the path where the  
image recording device would have been located for recording an  
image including the corresponding optical ray;

calculating a time associated with the determined  
position;

25 selecting an image recorded closest to the calculated  
time.

84. The computer-readable medium of claim 79, wherein the  
step of selecting an image for each optical ray comprises:

30 determining the particular position on the path where the  
image recording device would have been located for recording an  
image including the corresponding optical ray;

calculating a time associated with the determined  
35 position;

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selecting a plurality of images recorded closest to the  
calculated time;

5 calculating a motion of objects in the selected images;  
and

creating a new image frame for the calculated time based  
on the computed motion of objects.

10 85. The computer-readable medium of claim 79, wherein the  
image data comprises a set of pixel values.

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